



Cloud Removal for Sentinel-2 By Progressively Spatio-Temporal Patch Group Learning

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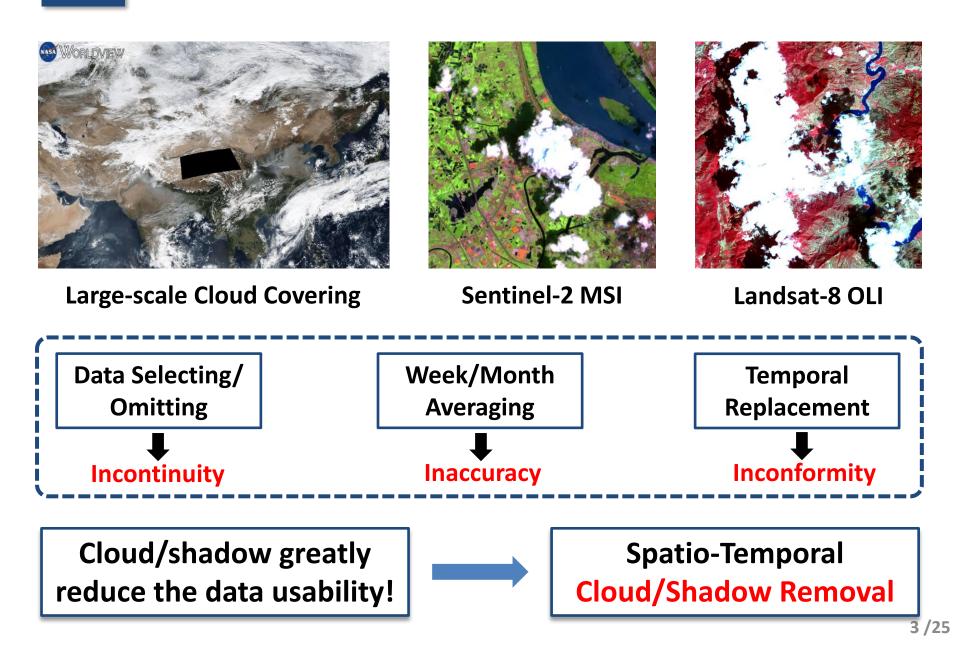
Sensing Symposium

2020.9.25



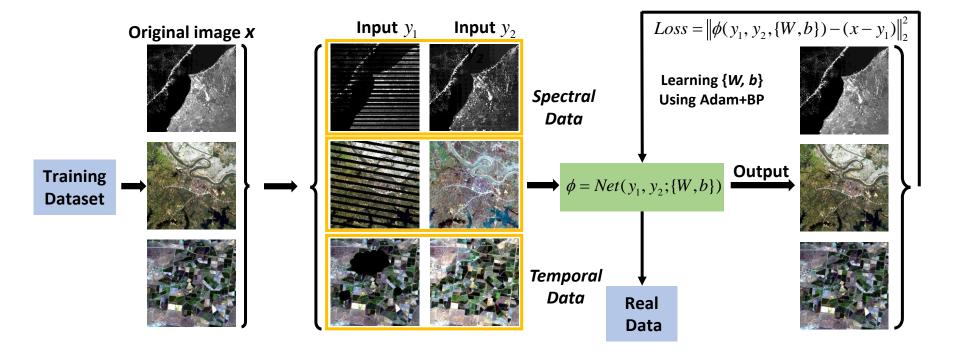


Background



Background

Our Pre-existing Work (STS-CNN) for Cloud Removal



- Joint Spatial-Temporal-Spectral Information
- End-to-end Learning Model through DCNN
- Unified Framework for Inpainting Missing Data

Zhang et al., IEEE TGRS, 2018. Code has been released! github.com/WHUQZhang

Background

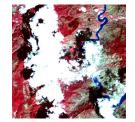
Deficiencies Analyzing of Pre-existing Works

1) Large-scale Cloud/Shadow Covering

- Marginal Differences
- Vague Texture

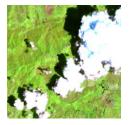
2) Need Ensure Integrity of Temporal Data

- Most Temporal Imageries are Fragmentary
- Limited in Actual Scenarios



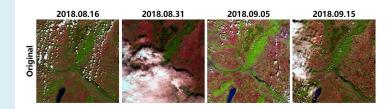






3) Multiple Sequence Temporal data

- Redundancy Complementary Information
- Complicated/Changeable Scenarios



Upgrade a new framework!

V1.0: STS

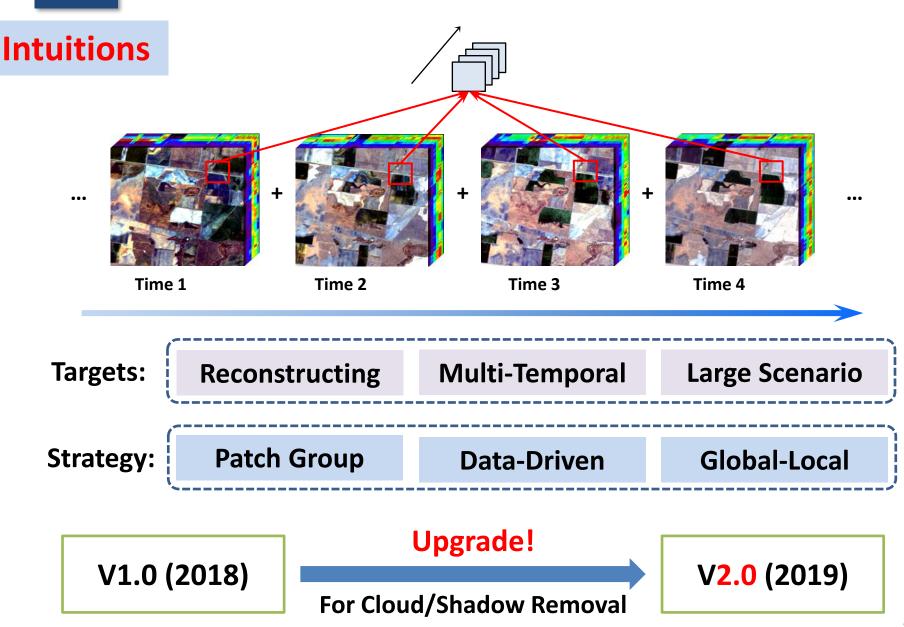
For Cloud/Shadow Removal







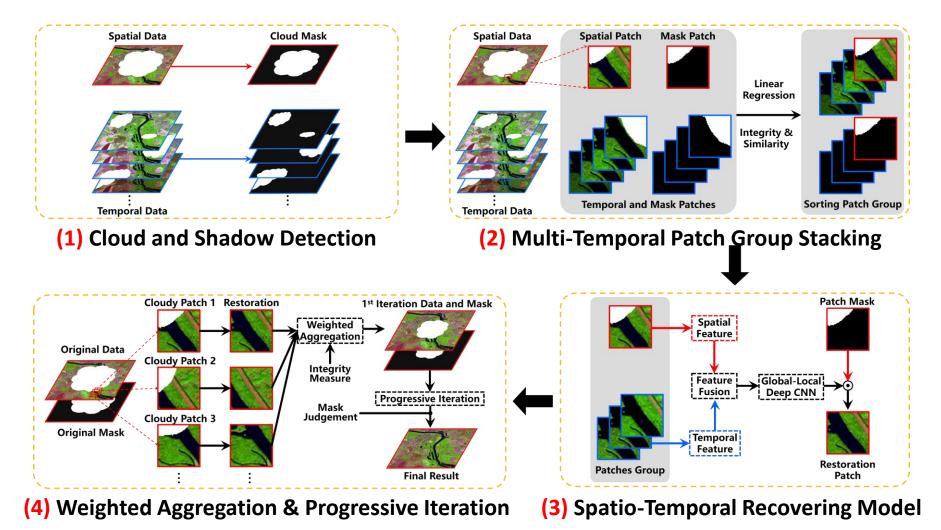
2



2

Methodology

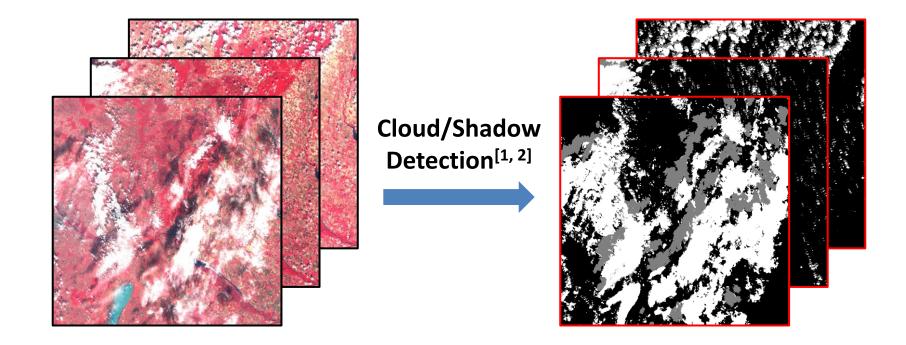
Flowchart of the Proposed Method



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(1) Multi-Temporal Imagery Cloud/Shadow Detection

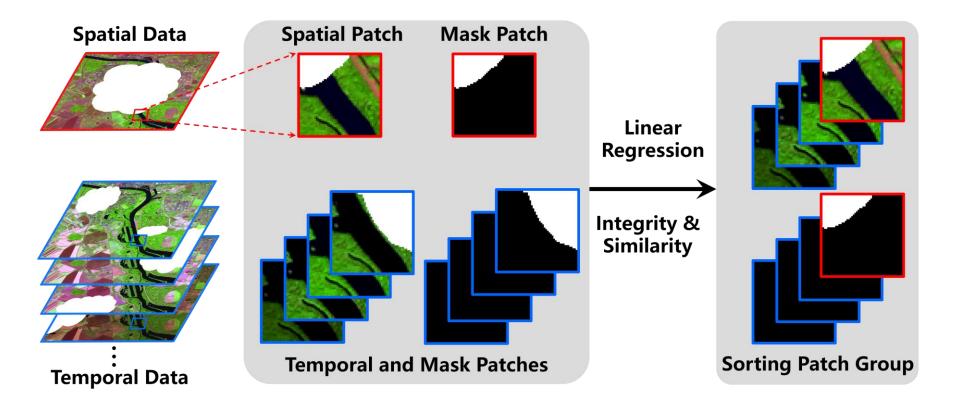


Obtaining Accurate Location of Cloud/Shadow for Reconstructing

[1] Fmask 4.0: S. Qiu *et al.*, RSE, 2019.
[2] MSCFF: Z. Li *et al.*, ISPRS, 2019.



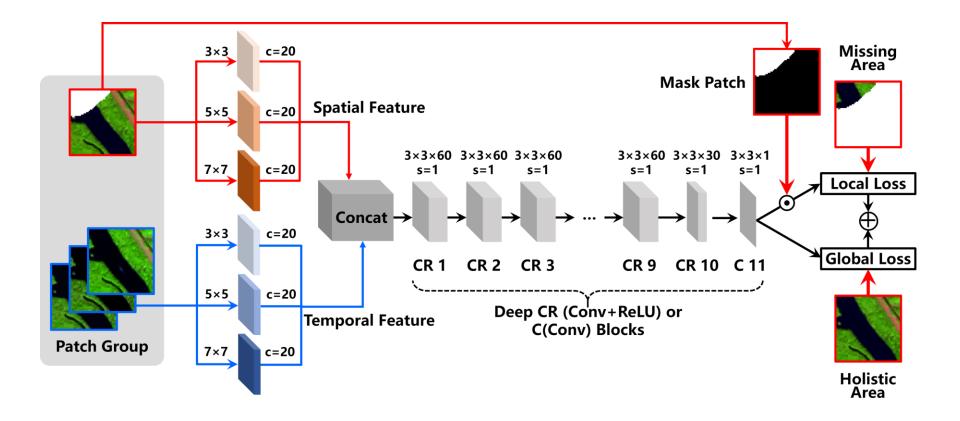
(2) Multi-Temporal Patch Group Stacking and Sorting



Building Spatio-Temporal Patch Group With High Correlation

(3) Spatio-Temporal Patch Group Recovering Model

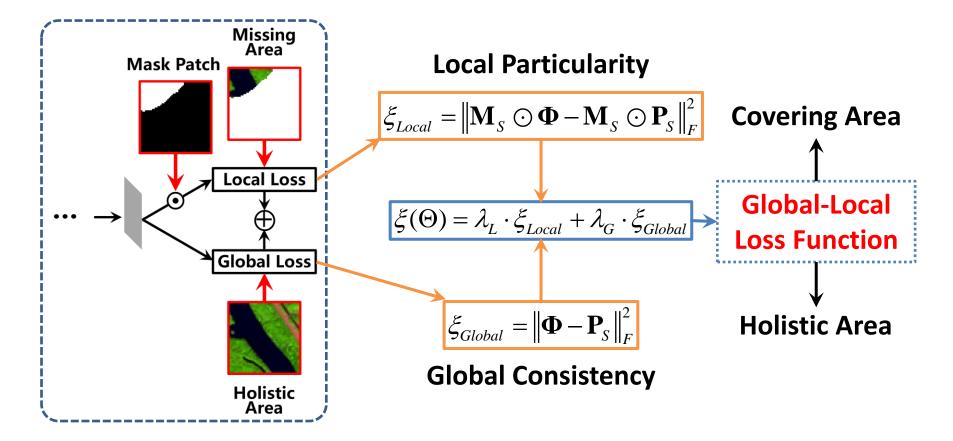
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Reconstructing Spatial Patch Covered by Cloud/Shadow

(3) Spatio-Temporal Patch Group Recovering Model

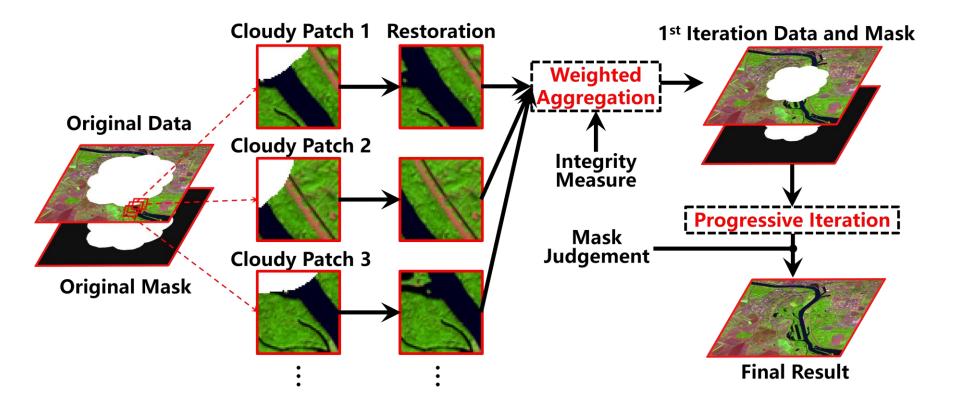
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Considering Global-Local Constraint for Recovering Spatial Patch

(4) Weighted Aggregation and Progressive Iteration

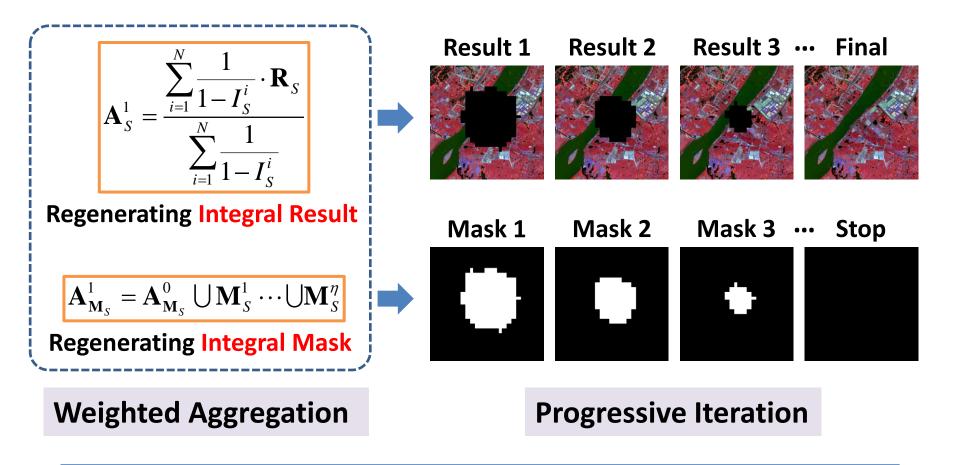
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Reconstructing Final Integral Result Through Multiple Restored Patches

(4) Weighted Aggregation and Progressive Iteration

2



Larger Integrity $I_S \rightarrow$ More Believable Spatial information





Simulated Experiments: Case 1 (Sentinel-2, Single Temporal)

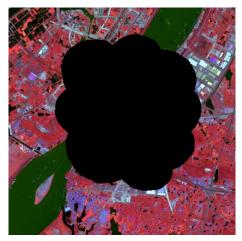


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(a) B05, B8A, B12



(d) STS By Zhang et al., TGRS, 2018



(b) Simulated Cloudy



(e) WLR By Zeng et al., RSE, 2013



(c) Temporal data



(f) Proposed

Simulated Experiments: Index Evaluation

3

Index	Ideal	Case 1				Case 2			
		Linear	WLR	STS	Proposed	Linear	WLR	STS	Proposed
CC	1	0.9270	0.9617	0.9395	0.9881	0.9689	0.9859	0.9772	0.9937
SSIM	1	0.7834	0.9083	0.8498	0.9414	0.9262	0.9623	0.9486	0.9814
RMSE	0	0.0843	0.0510	0.0722	0.0298	0.0486	0.0317	0.0403	0.0213

0.6

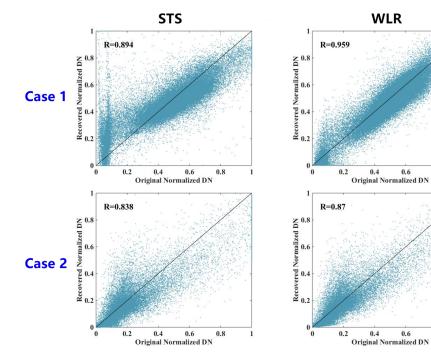
0.6

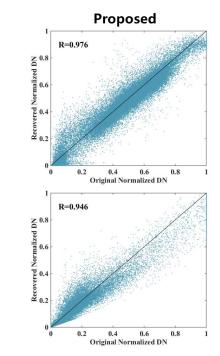
0.8

1

0.8

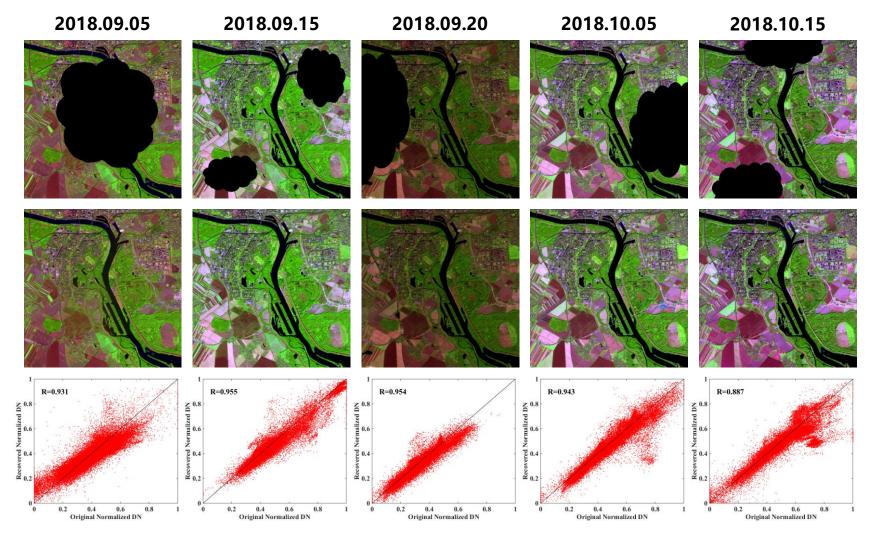
1



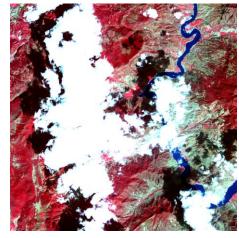


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Simulated Experiments: Case 3 (Sentinel-2, Multi-Temporal)



Real Experiments: (Sentinel-2 MSI, Single Temporal Data)

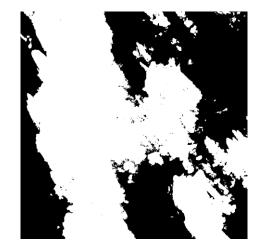


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(a) B05, B8A, B12



(d) STS



(b) Cloud Mask



(e) WLR



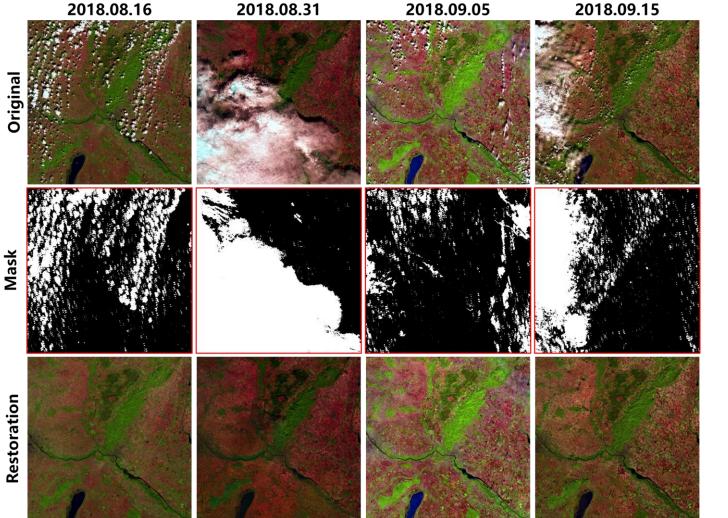
(c) Temporal



(f) Proposed

Real Experiments: (Sentinel-2 MSI, Multi-Temporal Data)

3



Whole Scene 5490×5490

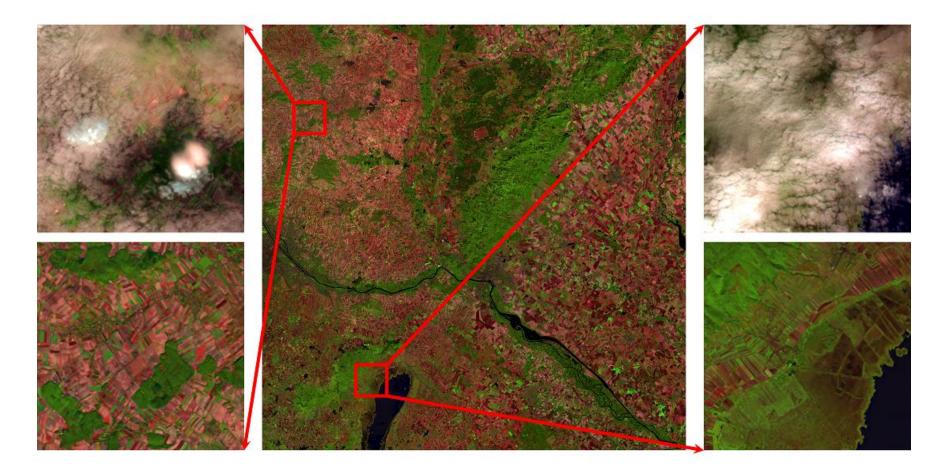
By MSCFF

Results By Proposed

3

Experiments

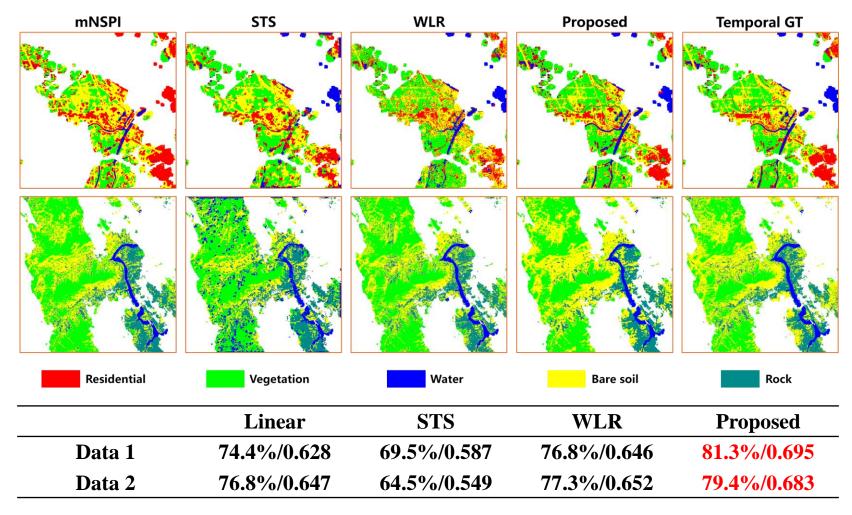
Real Experiments: (Multi-temporal, Large-Scale Scenarios)



Global and Two Local Amplification Results In 2018.09.15

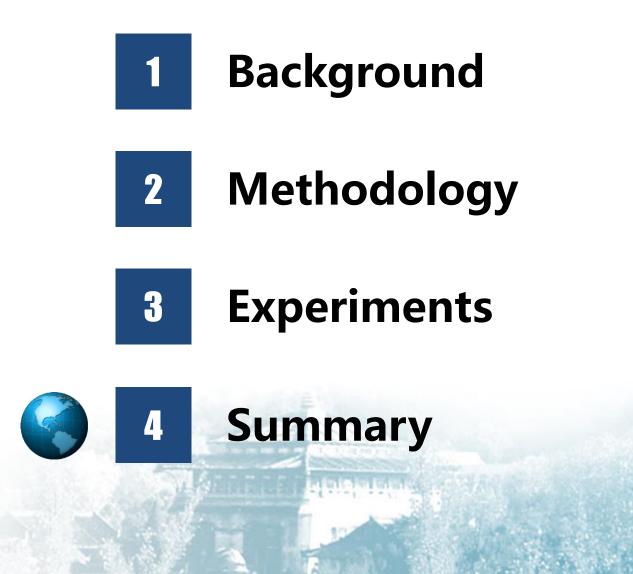
Discussion: Validation of the Restoring Results

3



Supervised Land Cover Evaluation Index (OA/Kappa)





Summary

Conclusions

Spatio-Temporal Patch Group Cloud Removal Framework

- Cloud and Shadow Detection
- Multi-Temporal Patch Group Stacking
- Spatio-Temporal Recovering Model
- Weighted Aggregation and Progressive Iteration

Deficiencies and Future Works

- Mask Type (Thick Cloud, Thin Cloud, and Shadow)
- Patch Group (Patch Size, Aggregating Weights, Global-Local...)
- Spatial Self-Reconstructing under no Temporal Information
- For Other Satellite Products Recovering (AOD, LST, NDVI...)









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Released Codes